

Jig-Shape Optimization of Quiet Supersonic Technology X-plane

Prepared For:

Fall 2017 Aerospace Flutter and Dynamics Council (AFDC) Meeting
Sedona, AZ

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Overview

- ☐ **Theoretical background (slides 4-10)**
- ☐ **Computational validation (slides 12-26)**
- ☐ **Conclusions (slide 27)**

Theoretical background





Introduction

❑ Supersonic Commercial Transport Aircraft Design

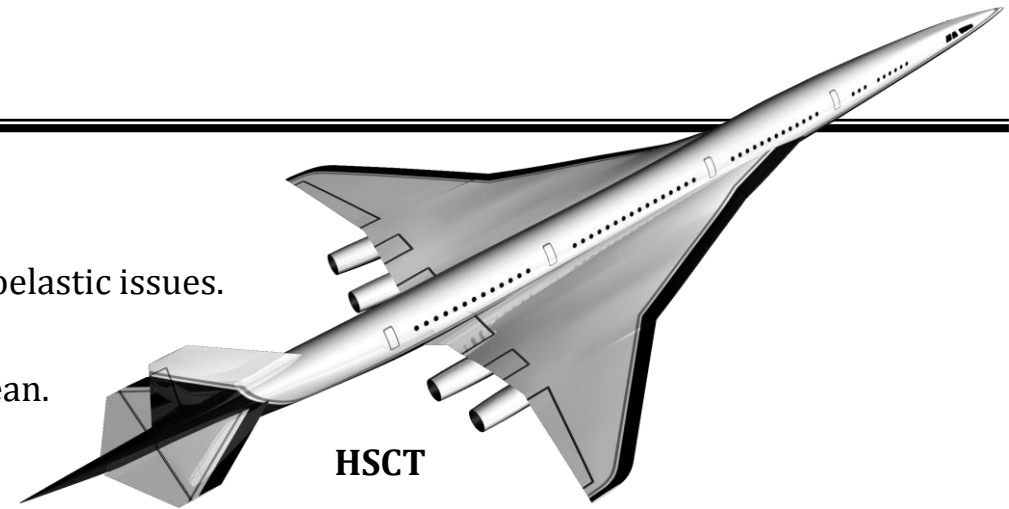
- ❖ Safety
 - Light weight airframe can cause strength, buckling, aeroelastic, and aeroservoelastic issues.
- ❖ Sonic boom
 - Supersonic flight of “commercial transport” aircraft allowed only over the ocean.
 - Perceived Loudness in decibels
 - ✓ **NASA's N+2 goal: 75 PLdB**
 - ✓ Concorde: **104 PLdB**
 - ✓ High Speed Civil Transport (HSCT): **99 PLdB**
- ❖ Fuel efficiency
 - Light weight airframe
 - Reduced drag

❑ Developing Quiet Supersonic Technology (QueSST) X-plane

- ❖ Low Boom Flight Demonstrator (LBFD)
- ❖ Lockheed Martin Skunk Works is the prime contractor for preliminary design.
- ❖ **Loudness: 74 PLdB**

❑ Major Issue

- ❖ Out-mold-line configuration of an aircraft is design for the desired aerodynamic performance. Assume rigid structure.
- ❖ Flexibility of the structure changes the aerodynamic performance.
- ❖ It has been reported that one degree of the tip twist of a LBFD wing and stabilator under the cruise flight condition can increase the sonic boom level by 0.2 PLdB and 1.3 PLdB, respectively.





Jig-Shape Optimization Problem Statement

□ Assume unconstrained Optimization

□ Optimization Problem Statement

❖ Find design variables: $\{X\} = [X_1, X_2, \dots, X_{ndv}]^T$ which

$$\text{minimize } \left\{ F(X) = \sum_{j=1}^{nsurf3} \Delta T_j^2 \right\}$$

❖ $\{\Delta T\} \equiv \{T\}_t - \{T\}_d$

❖ $\{T\}_t$ = target trim shape at surface GRIDs

➤ Sonic boom level is computed based on target trim shape.

❖ $\{T\}_d$ = trim shape based on design jig shape

➤ $\{jig\}_d \xrightarrow[\text{trim analysis}]{} \{T\}_d$

➤ $\{jig\}_d \equiv \{jig\}_b + \{\Delta jig\}$

✓ $\{jig\}_d$ = design jig-shape

✓ $\{jig\}_b$ = baseline jig-shape

✓ $\{\Delta jig\}$ = jig-shape changes

➤ $\{\Delta jig\} = [\Phi]\{X\}$

✓ X_i = i-th design variable

✓ $[\Phi] = [\{\phi\}_1 \{\phi\}_2 \dots \{\phi\}_{ndv}]$

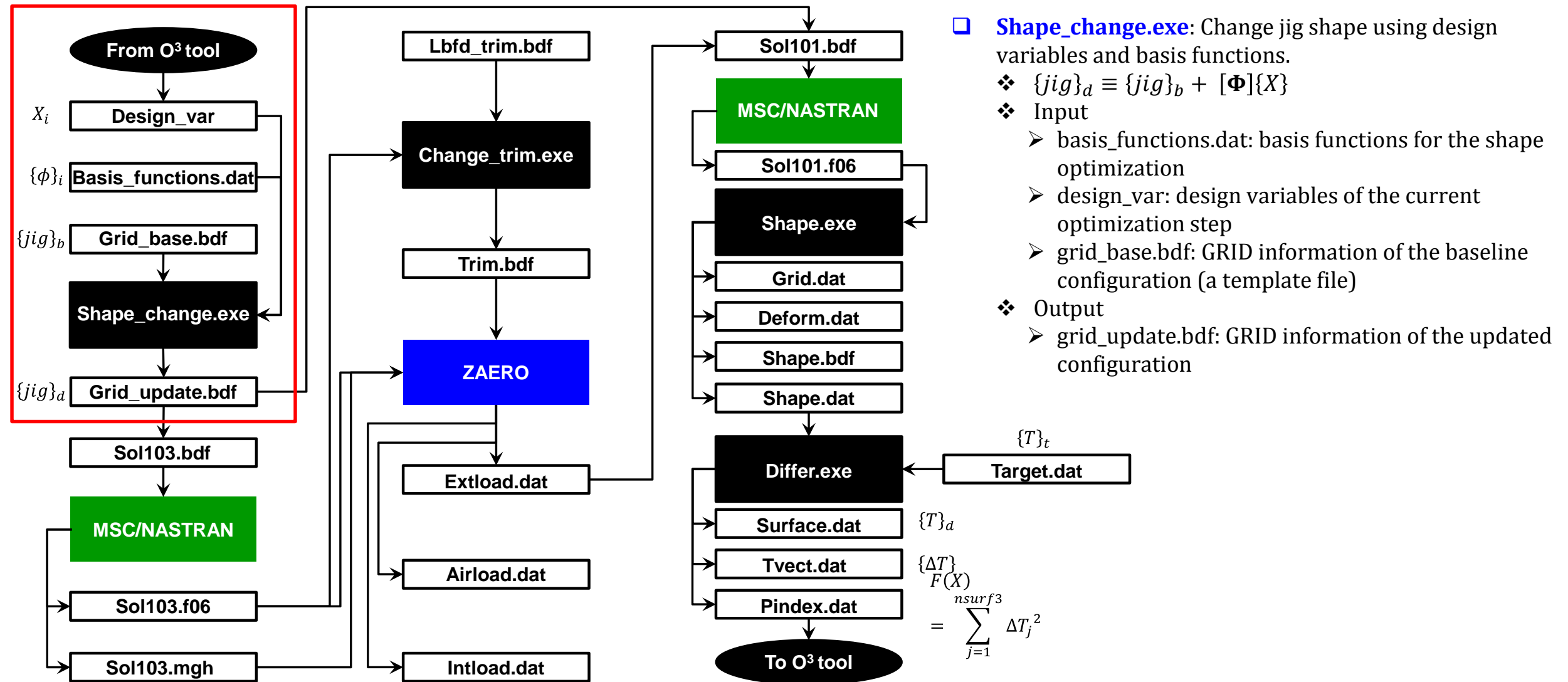
• $\{\phi\}_i$ = i-th basis function

■ Eigen vector based on jig shape

■ Eigen vectors are normalized as Max deflection = 1 inch.



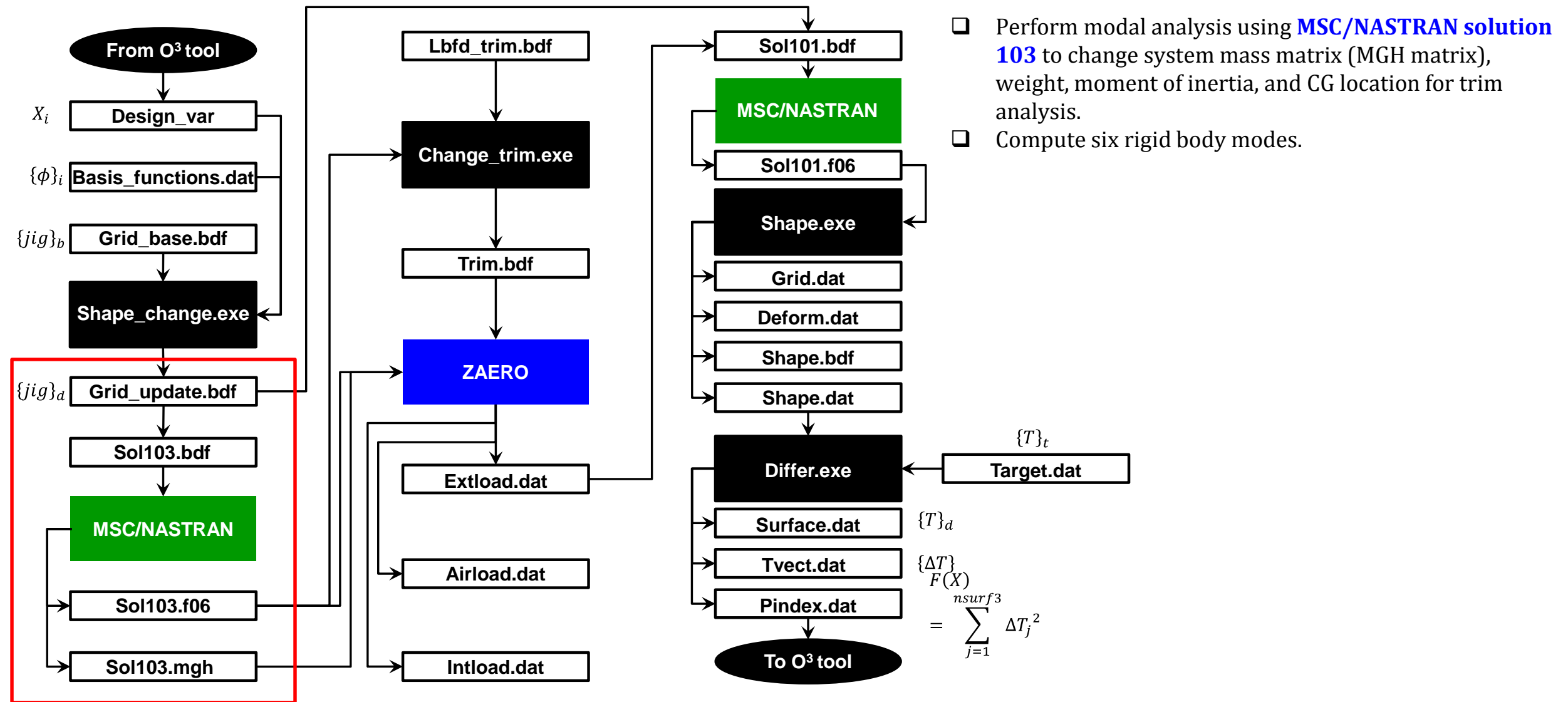
Update Jig-Shape Module: using shape_change.exe



Change jig shape using design variables & basis functions.



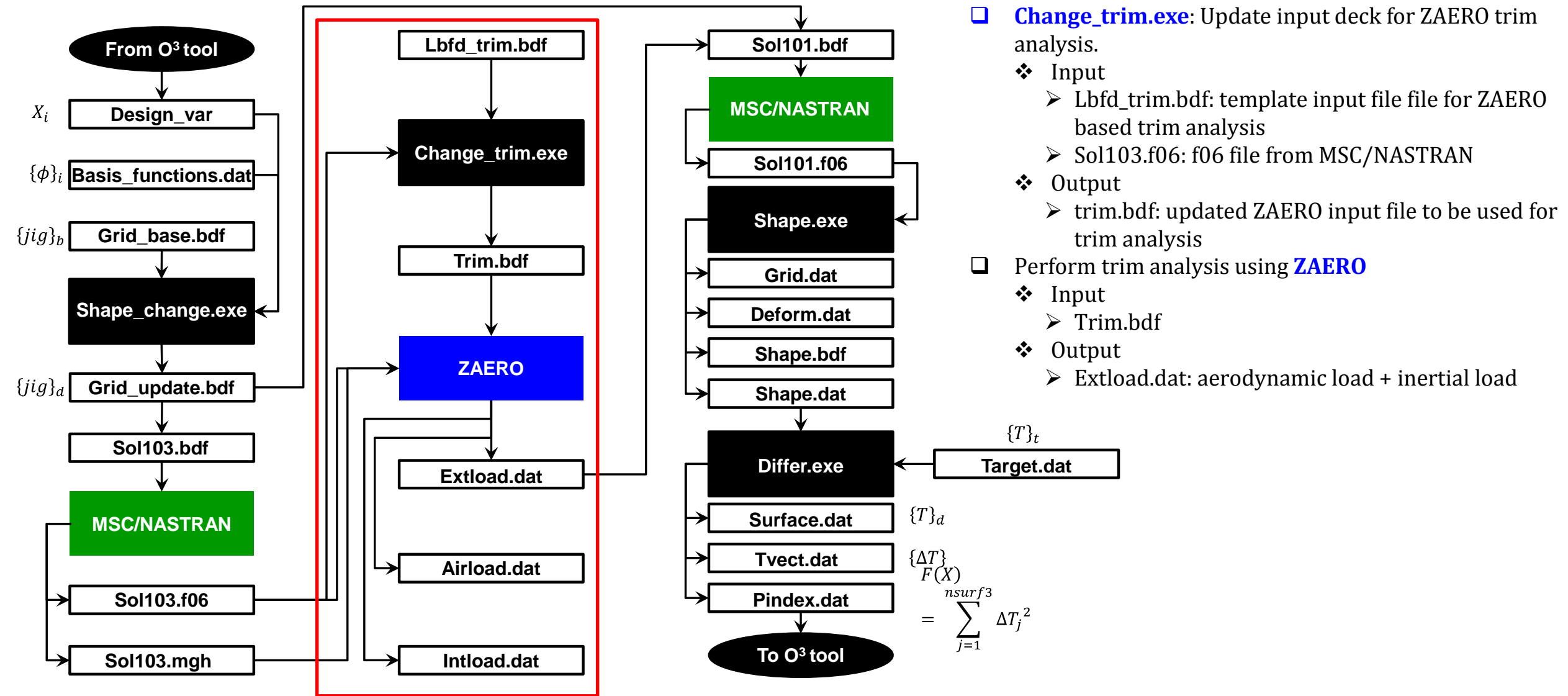
Modal Analysis Module: using MSC/NASTRAN solution 103



Change mode shapes, weight, moment of inertia, & CG location for trim analysis.



Trim Analysis Module: using ZAERO & change_trim.exe



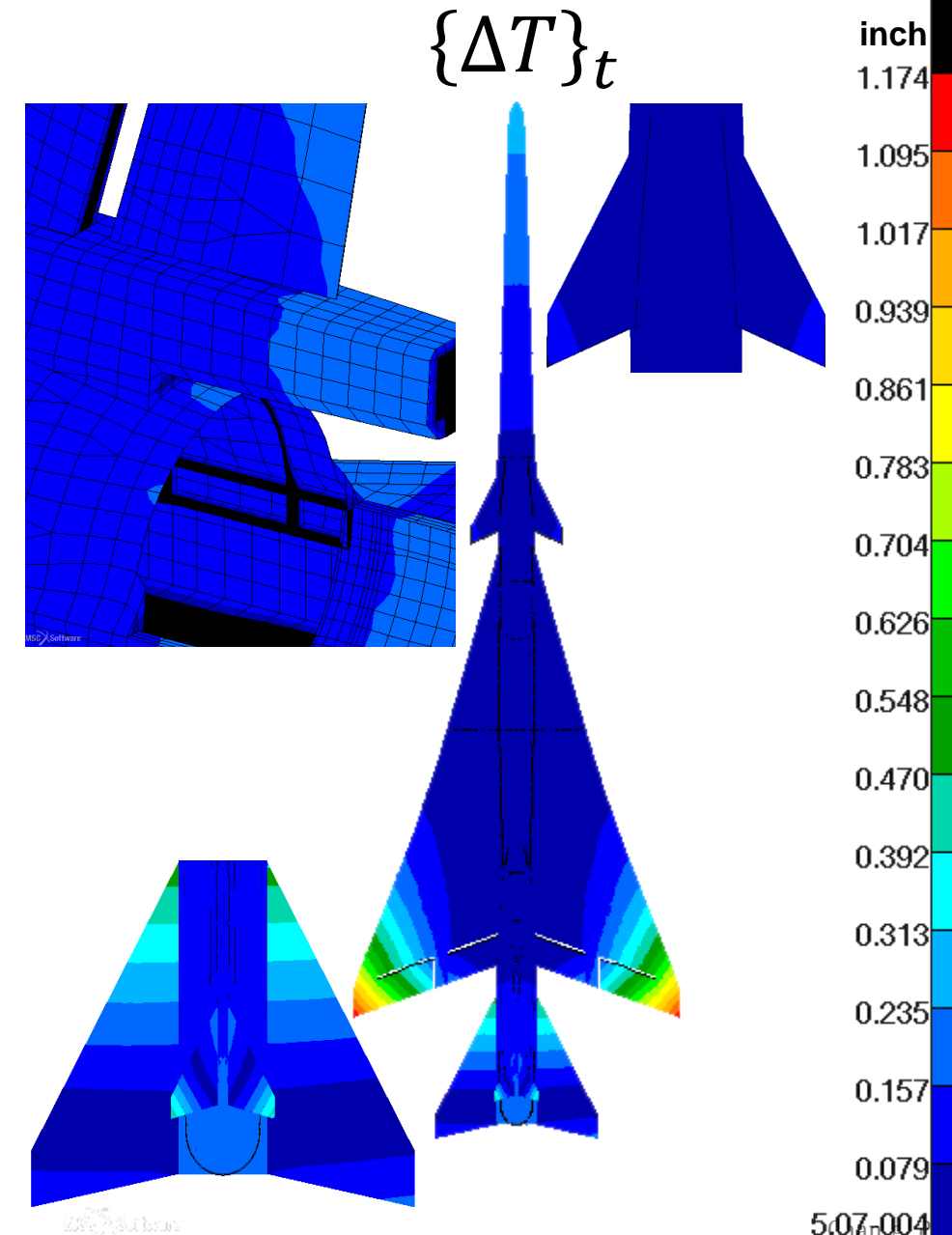
Compute external load using ZAERO code.





Compute Starting Design Variables: Using Least Squares Surface Fitting Technique

- $\{\Delta T\}_t \equiv \{T\}_t - \{T\}_b$
 - ❖ $\{T\}_t$ = target trim shape at surface GRIDs
 - ❖ $\{T\}_b$ = trim shape based on the baseline jig-shape
 - $\{jig\}_b \xrightarrow{\text{trim analysis}} \{T\}_b$
- Fitting $\{\Delta T\}_t$ surface using perturbed shapes $\{\Delta T\}_i, i = 1, 2, \dots, ndv$
 - ❖ Perturb baseline jig-shape using basis functions $[\Phi]$
 - $\{jig\}_d \equiv \{jig\}_b + [\Phi]\{X\}$
 - Where, $\{\phi\}_i$ = i-th basis function
 - $\{jig\}_b + \{\phi\}_i \xrightarrow{\text{trim analysis}} \{T\}_i$
 - $\{\Delta T\}_i \equiv \{T\}_i - \{T\}_b$ (i-th perturbed shape)
 - ❖ Define a matrix: $[\Psi] = [\{\Delta T\}_1 \{\Delta T\}_2 \dots \{\Delta T\}_{ndv}]$
- $[\Psi]\{X\} = \{\Delta T\}_t$
 - ❖ $[\Psi]^T[\Psi]\{X\} = [\Psi]^T\{\Delta T\}_t$
 - ❖ $([\Psi]^T[\Psi])^{-1}[\Psi]^T[\Psi]\{X\} = ([\Psi]^T[\Psi])^{-1}[\Psi]^T\{\Delta T\}_t$
- Starting design variables: $\{X\} = ([\Psi]^T[\Psi])^{-1}[\Psi]^T\{\Delta T\}_t$



Computational validation





Thickness & camber effect



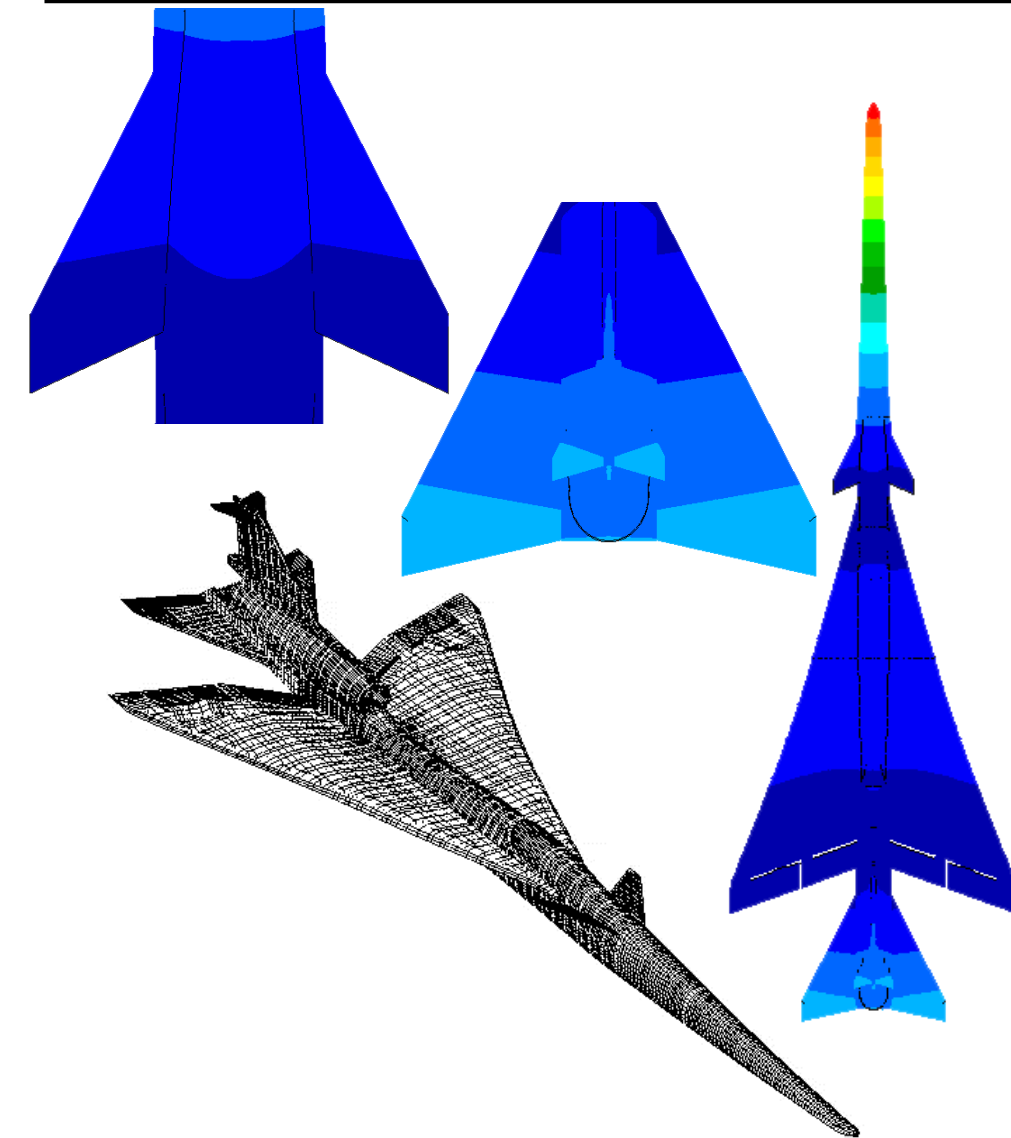
Summary of Natural Frequencies (Baseline Configuration)

Mode	Frequency (Hz)			Notes
	Baseline	Optimum	% difference	
7	5.634			First fuselage bending
9	9.045			First wing bending + forward fuselage vertical bending + stabilator rotation
11	11.97			Forward fuselage vertical bending + first wing bending + stabilator rotation (Asymmetric)
15	14.76			Stabilator rotation
17	19.23			Wing tip bending + T-tail rotation + flap bending (Asymmetric)
19	20.08			T-tail rotation (Asymmetric)
20	20.54			Wing tip bending + T-tail rotation + aileron rotation + flap bending + forward fuselage vertical bending (Asymmetric)
22	21.75			Aileron rotation + flap rotation + T-tail bending + outboard wing bending torsion
23	22.16			Flap rotation + aileron rotation + wing tip bending + T-tail bending (Asymmetric)
25	22.70			Flap rotation + aileron rotation + T-tail bending (Asymmetric)
37	30.79			Canard bending
48	42.96			T-tail bending (Asymmetric)

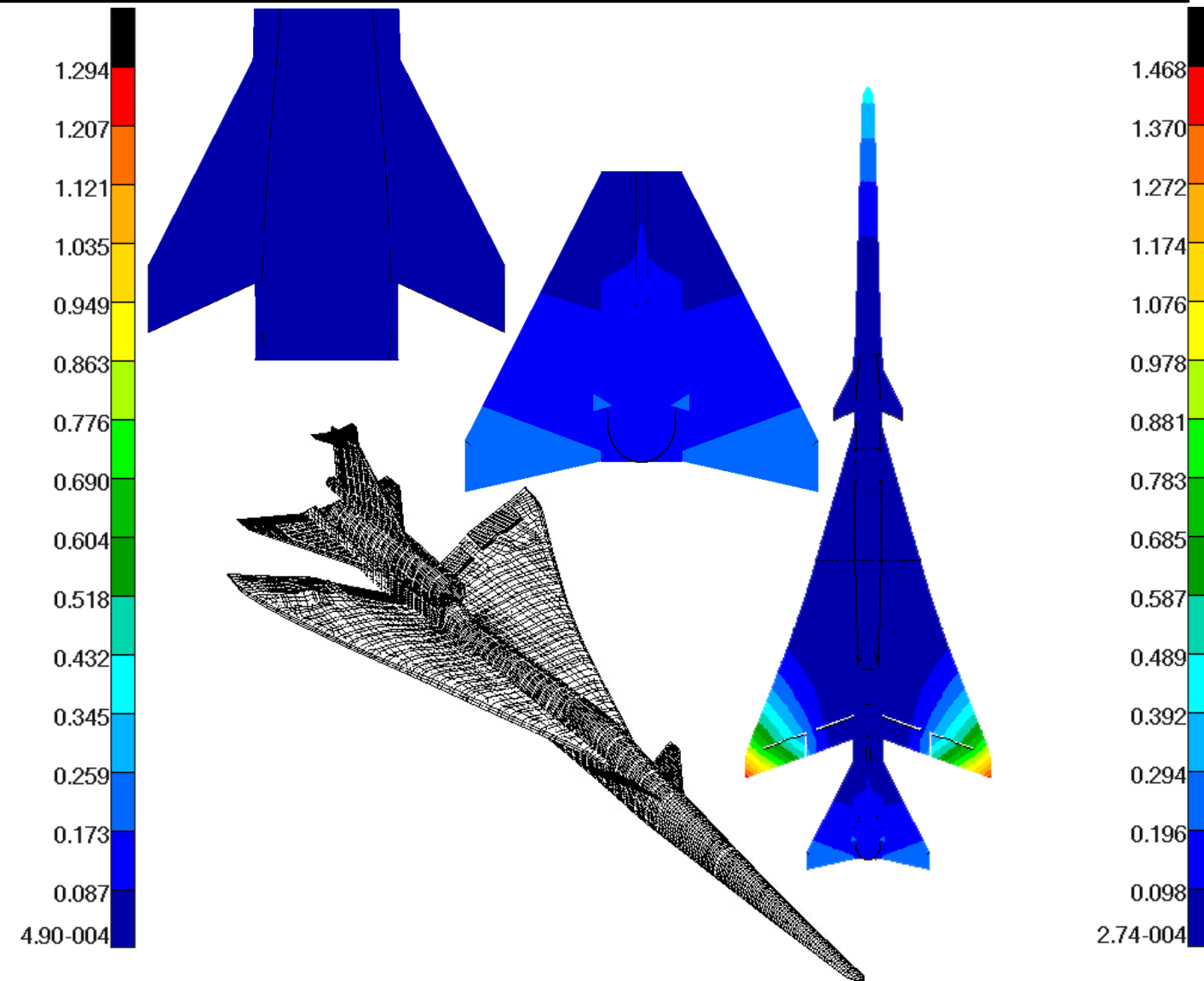


Mode 7: 5.634 Hz

Mode 9: 9.045 Hz



first fuselage vertical bending

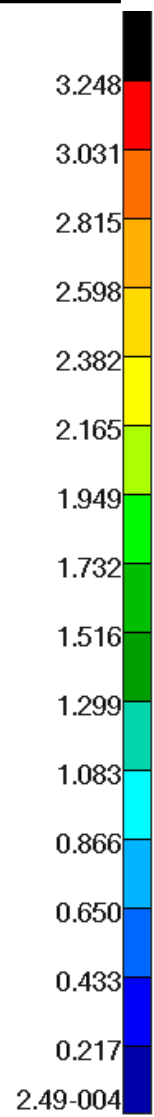
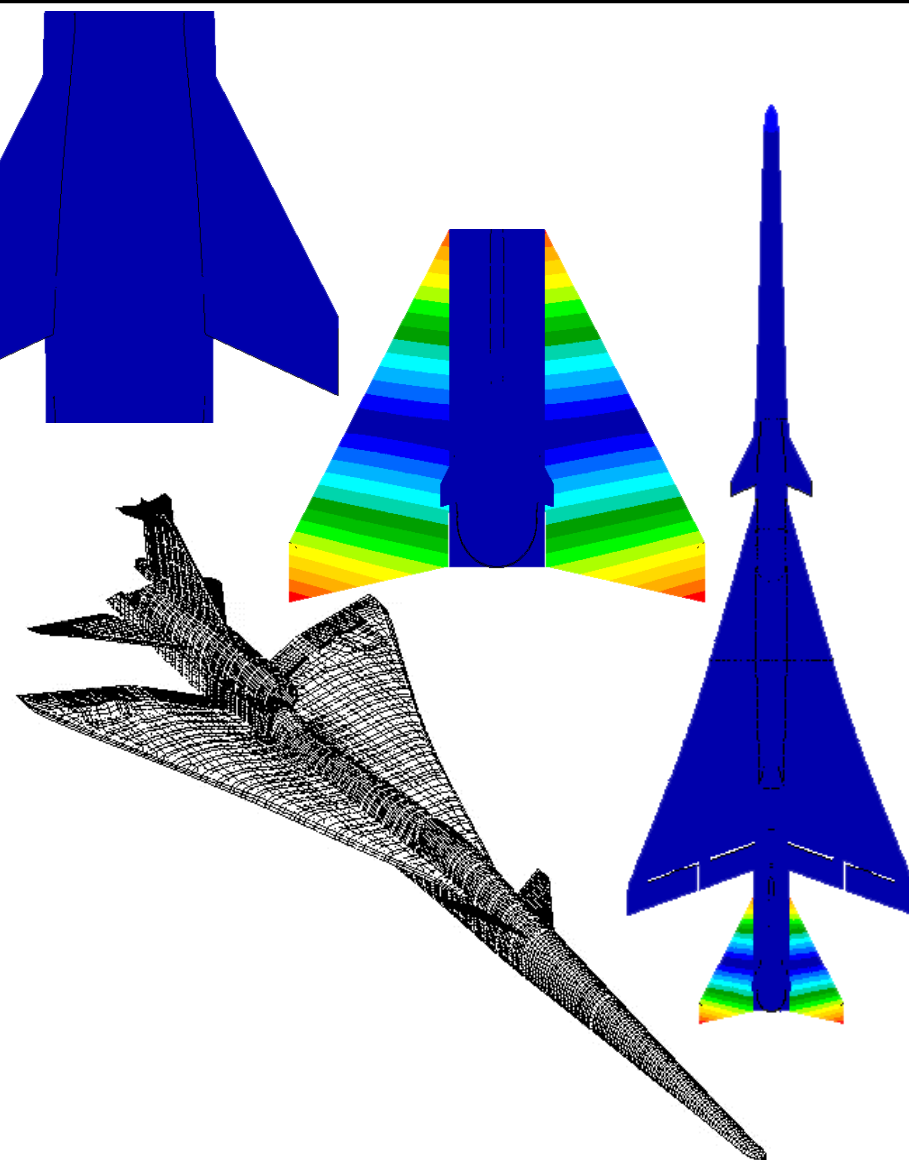
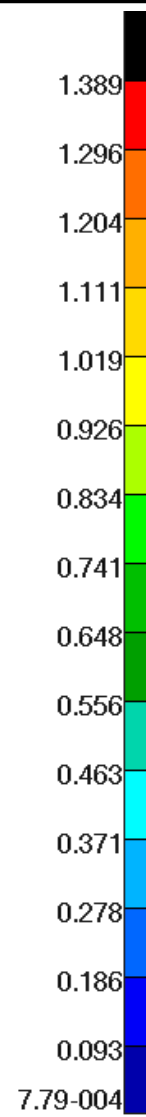
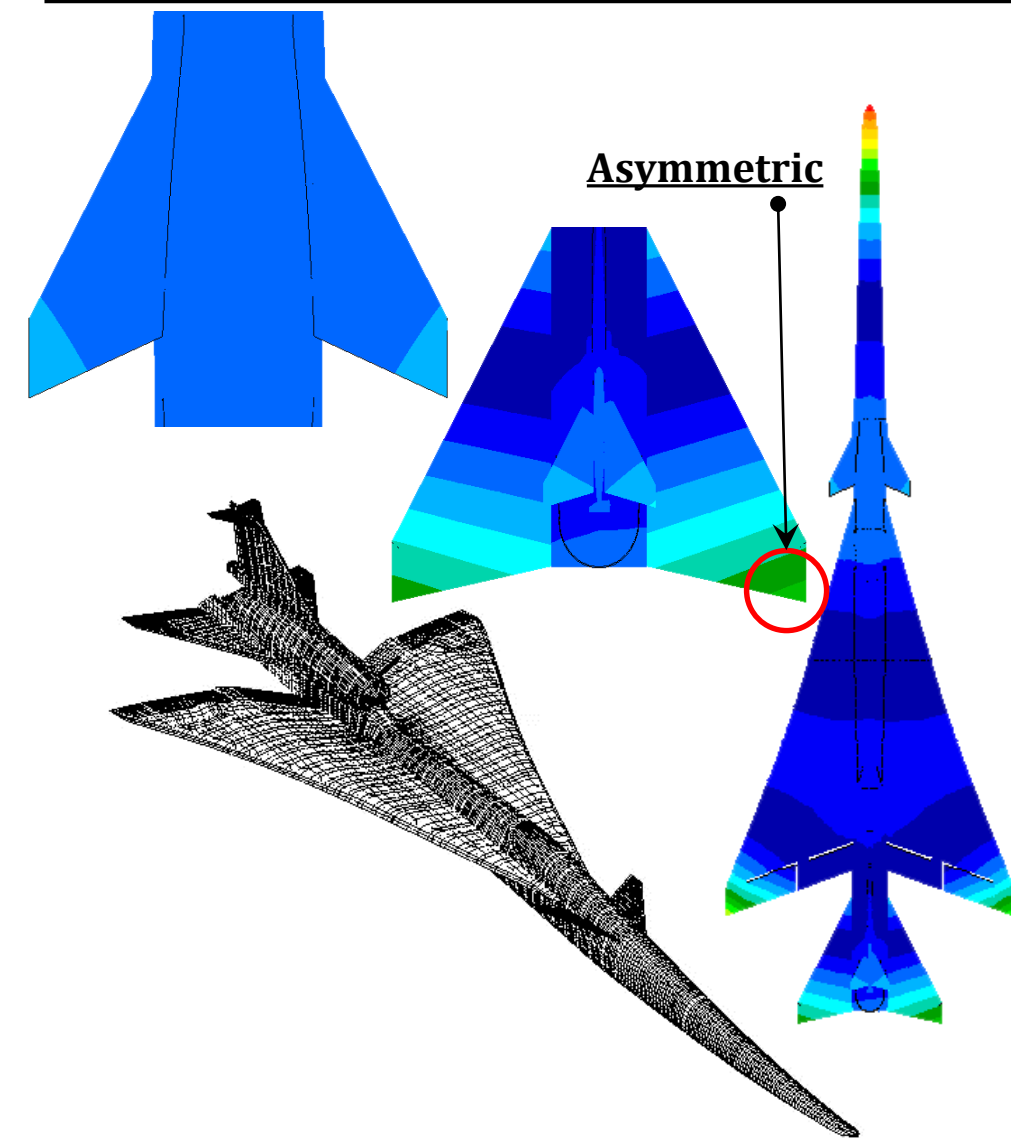


Symmetric first wing bending + forward fuselage vertical bending + horizontal tail rotation (in-phase: forward fuselage & wing)(out-phase: wing and horizontal tail)



Mode 11: 11.97 Hz

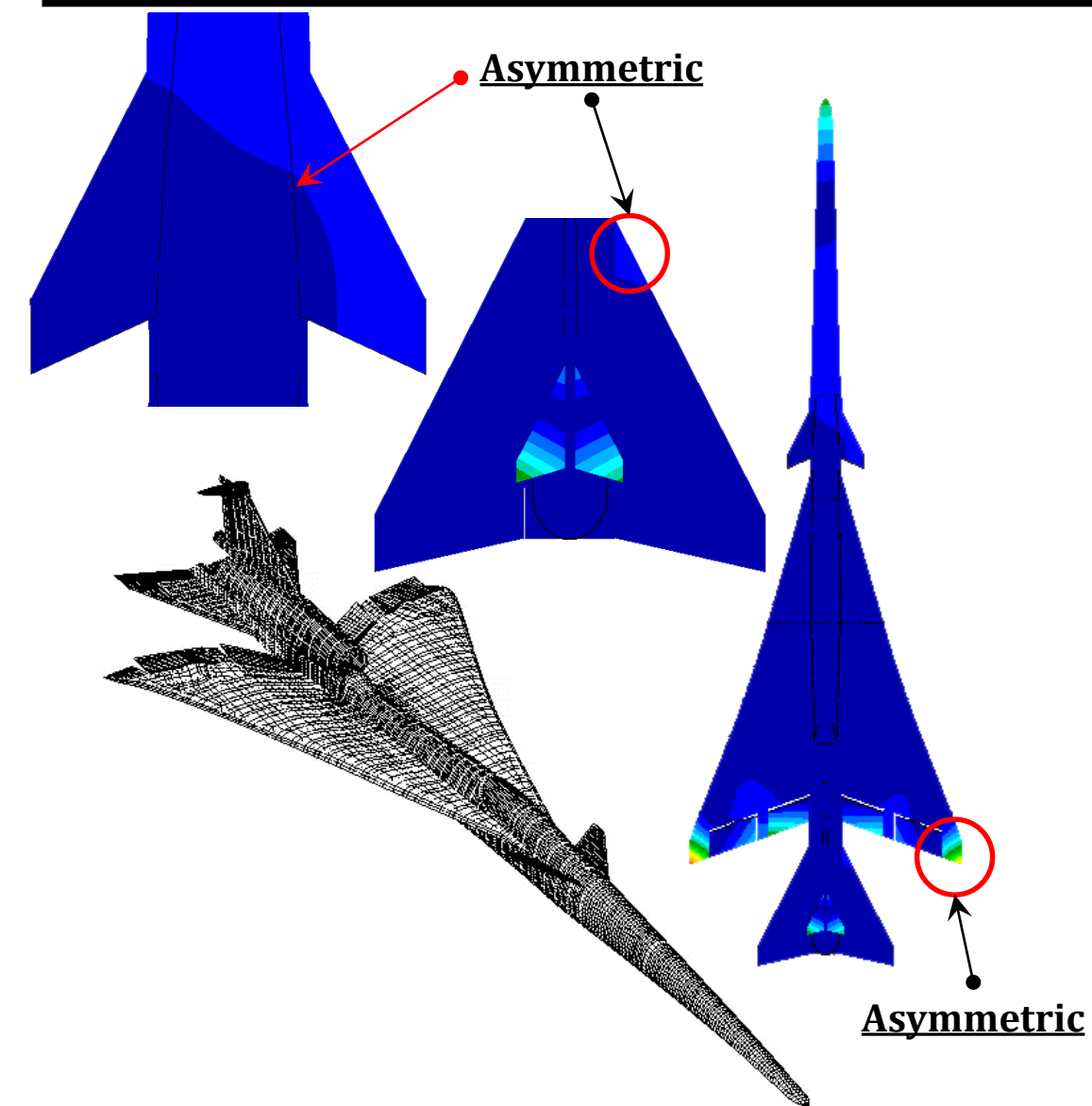
Mode 15: 14.76 Hz



Symmetric first wing bending + forward fuselage vertical bending + horizontal tail rotation (out-phase: forward fuselage & wing)(in-phase: wing and horizontal tail)

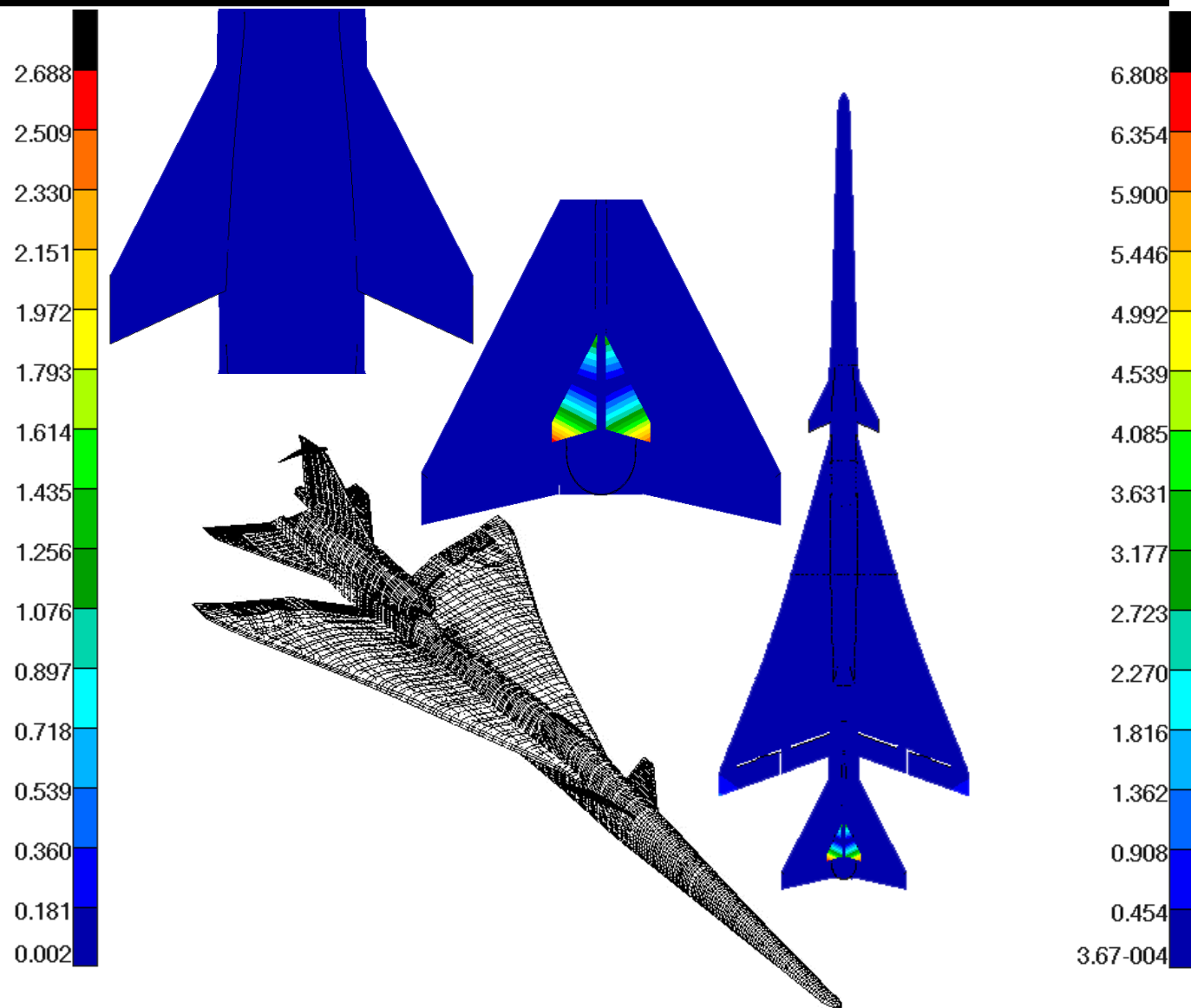
Symmetric horizontal tail rotation

Mode 17: 19.23 Hz



symmetric wing tip bending+Ttail rotation + flap

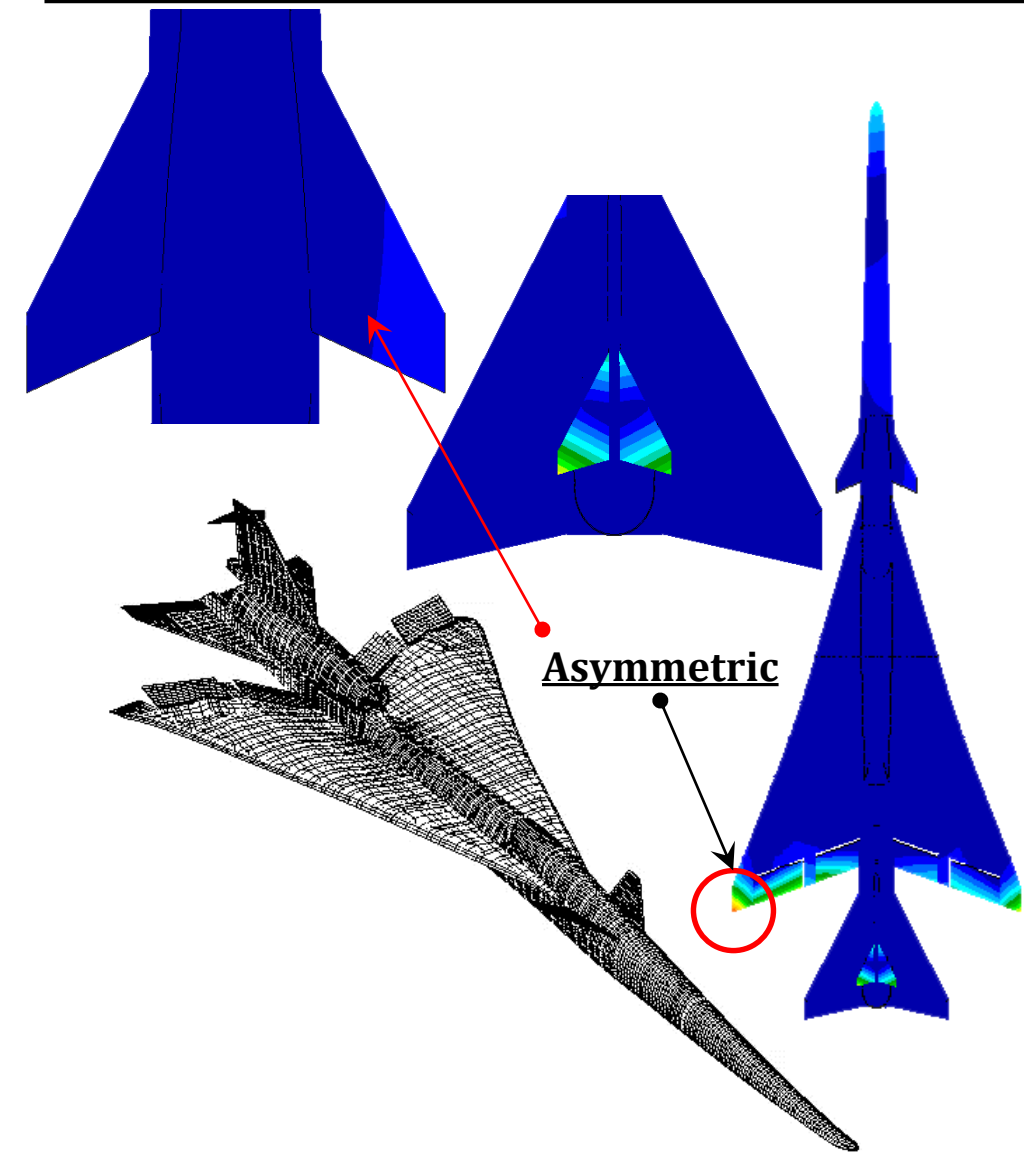
Mode 19: 20.08 Hz



symmetric ttail rotation

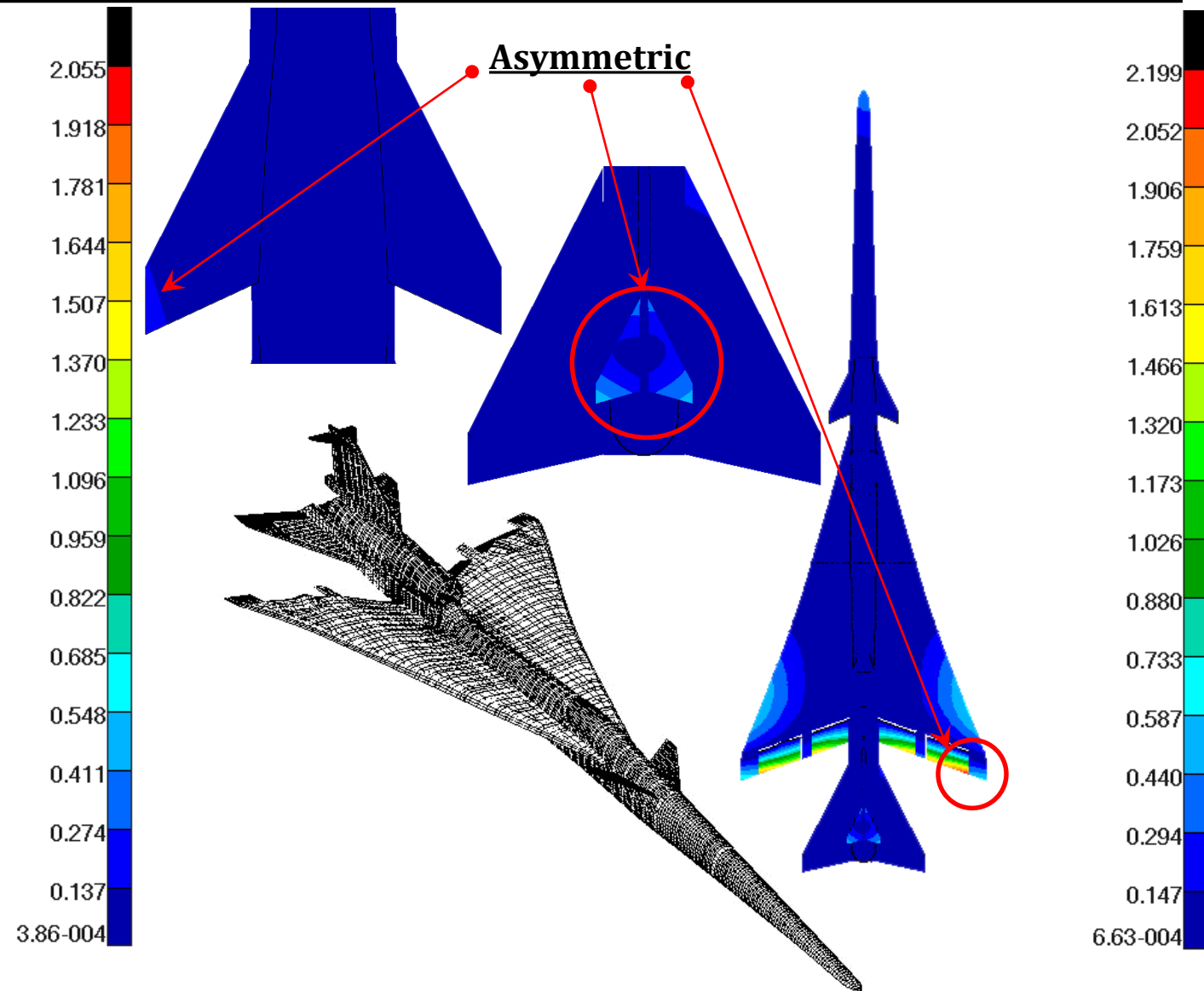


Mode 20: 20.54 Hz



symmetric wing tip bending + ttail rotation flap & aileron rotation + forward fuselage bending + nose landing gear vertical bending (out-phase wing tip & forward fuselage) (out phase wing tip & ttail)

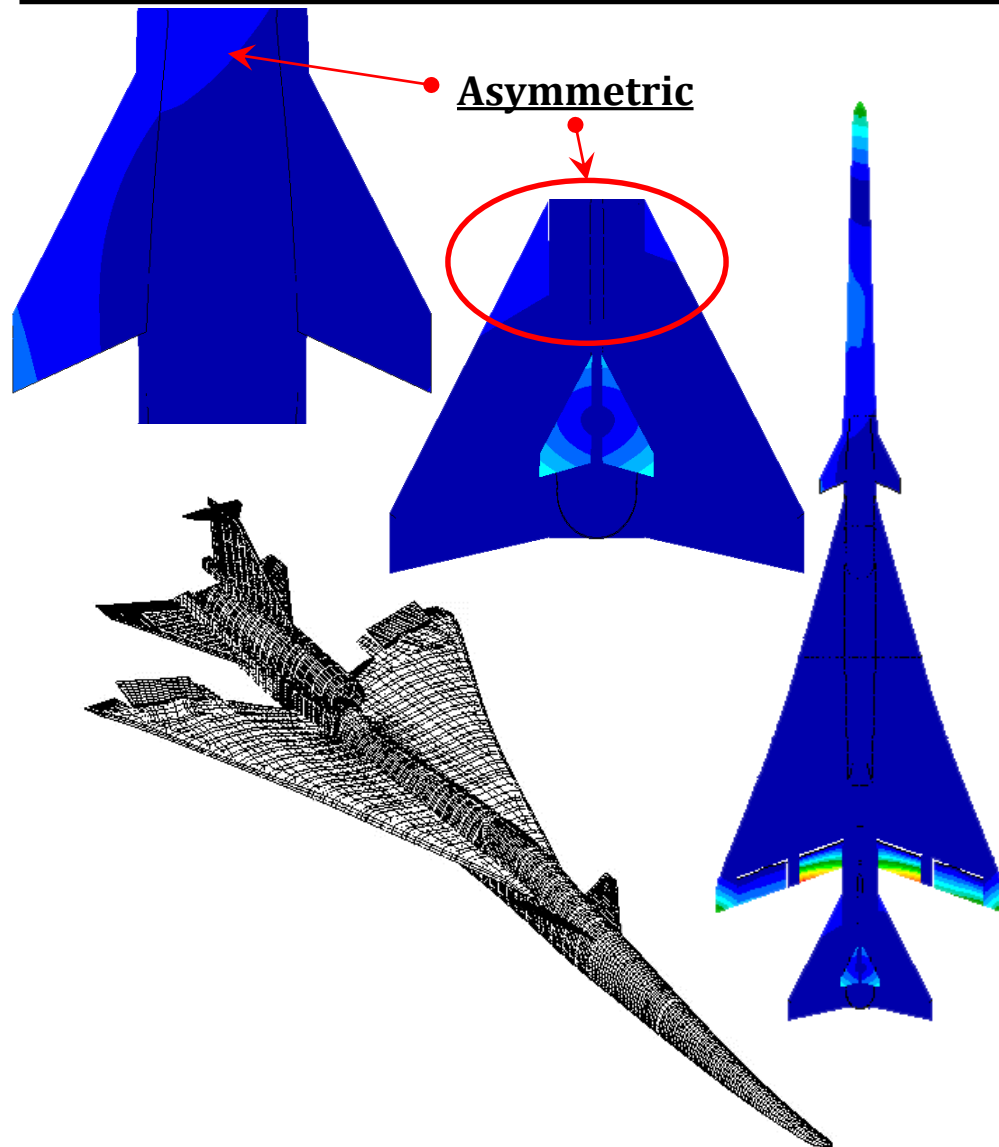
Mode 22: 21.75 Hz



symmetric aileron + flaperon (in-phase)+ttail(pitch +yaw)

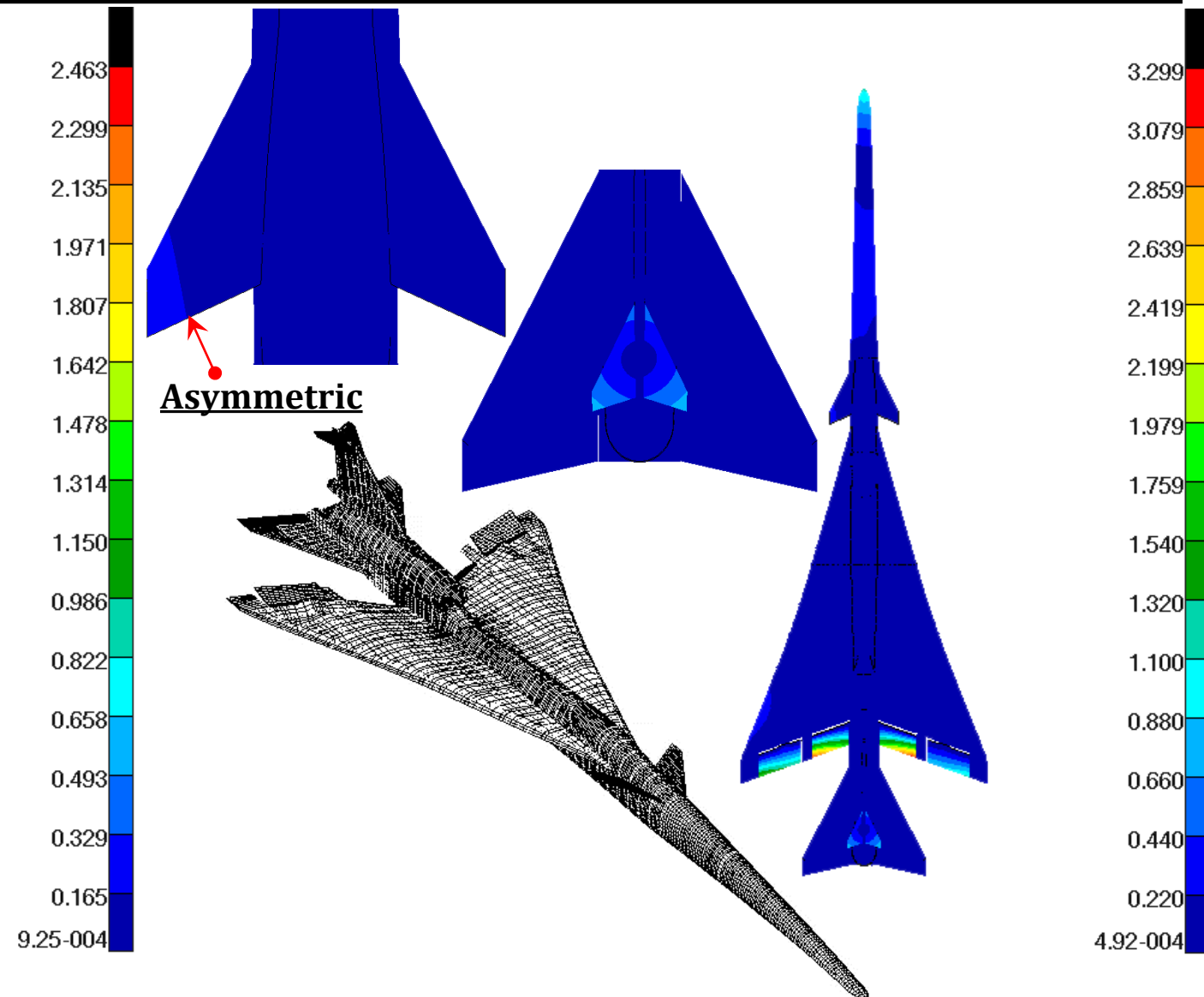


Mode 23: 22.16 Hz



symmetric Flaperon+airleron (out-phase) +ttail(pitch+yaw) +forward fulage and aileron(in-phase)

Mode 25: 22.70 Hz



symmetric flaperon+airleron (out-phase)+ttail(pitch+yaw) + forward fulage and aileron(out-phase)

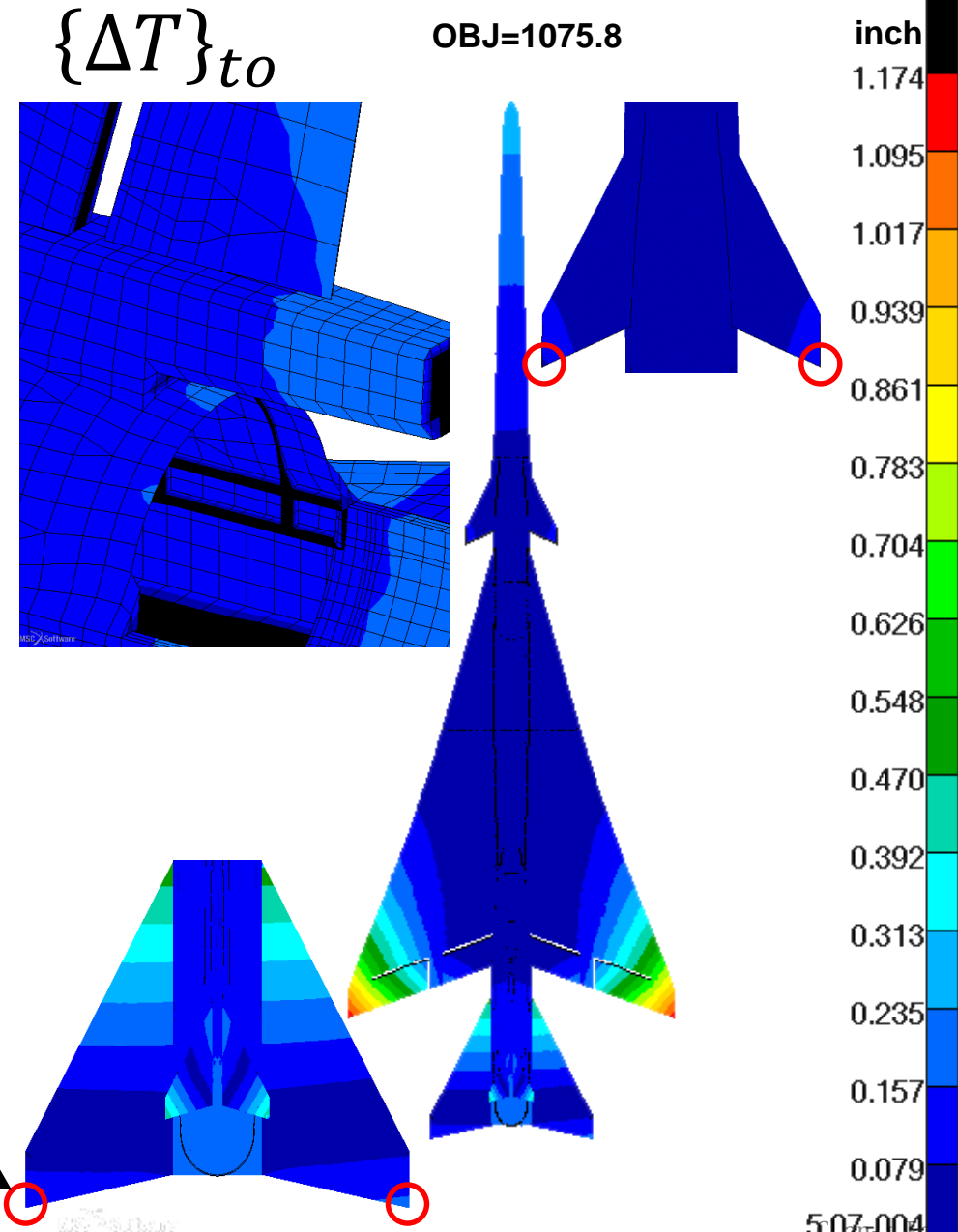


Trim Shape Difference (Baseline Configuration)

- ☐ Weight:
 - ❖ Cruise = 18499.99 lbf
- ☐ Forward CG location
 - ❖ x=836.09 inch, y=-0.1897 inch, z=100.68 inch
- ☐ Mach: 1.42
- ☐ Altitude: 55000 ft
- ☐ Aileron deflection angle: 0.5 deg
- ☐ T-tail deflection angle: 6.47 deg
- ☐ $\{\Delta T\}_{to} \equiv \{T\}_t - \{T\}_o$
 - ❖ $\{T\}_t$ = target trim shape at surface GRIDs
 - ❖ $\{T\}_o$ = trim shape based on optimum jig shape
 - ✓ $\{jig\}_o \equiv \{jig\}_b + [\Phi]\{X\}_o$
 - ✓ $\{jig\}_o \xrightarrow{\text{trim analysis}} \{T\}_o$

X_i	Value
1	0.0
2	0.0
3	0.0
4	0.0
5	0.0
6	0.0
7	0.0
8	0.0
9	0.0
10	0.0
11	0.0
12	0.0
13	0.0

Asymmetric



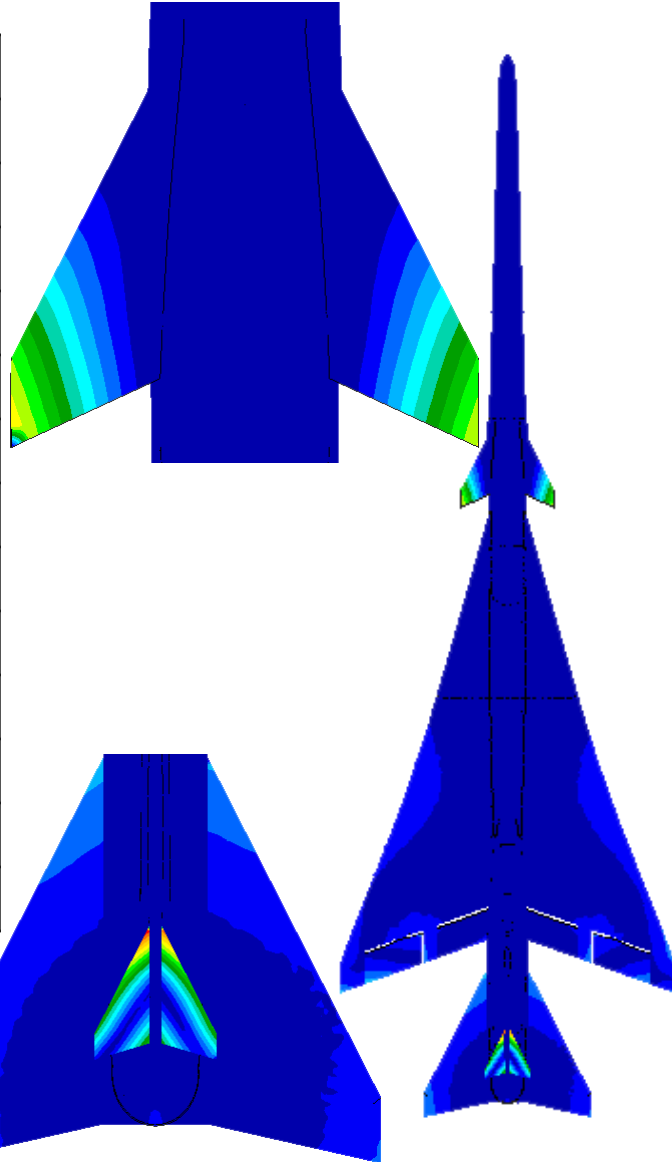


Optimization #1: $\{\Delta T\}_{to} = \{T\}_t - \{T\}_o$

Use least-squares surface fitting

OBJ = 17.48

X_i	Value
1	0.4370
2	-1.125
3	0.2469
4	0.4035
5	.02350
6	0.6273
7	.04194
8	-.02655
9	.000856
10	0.1141
11	
12	
13	

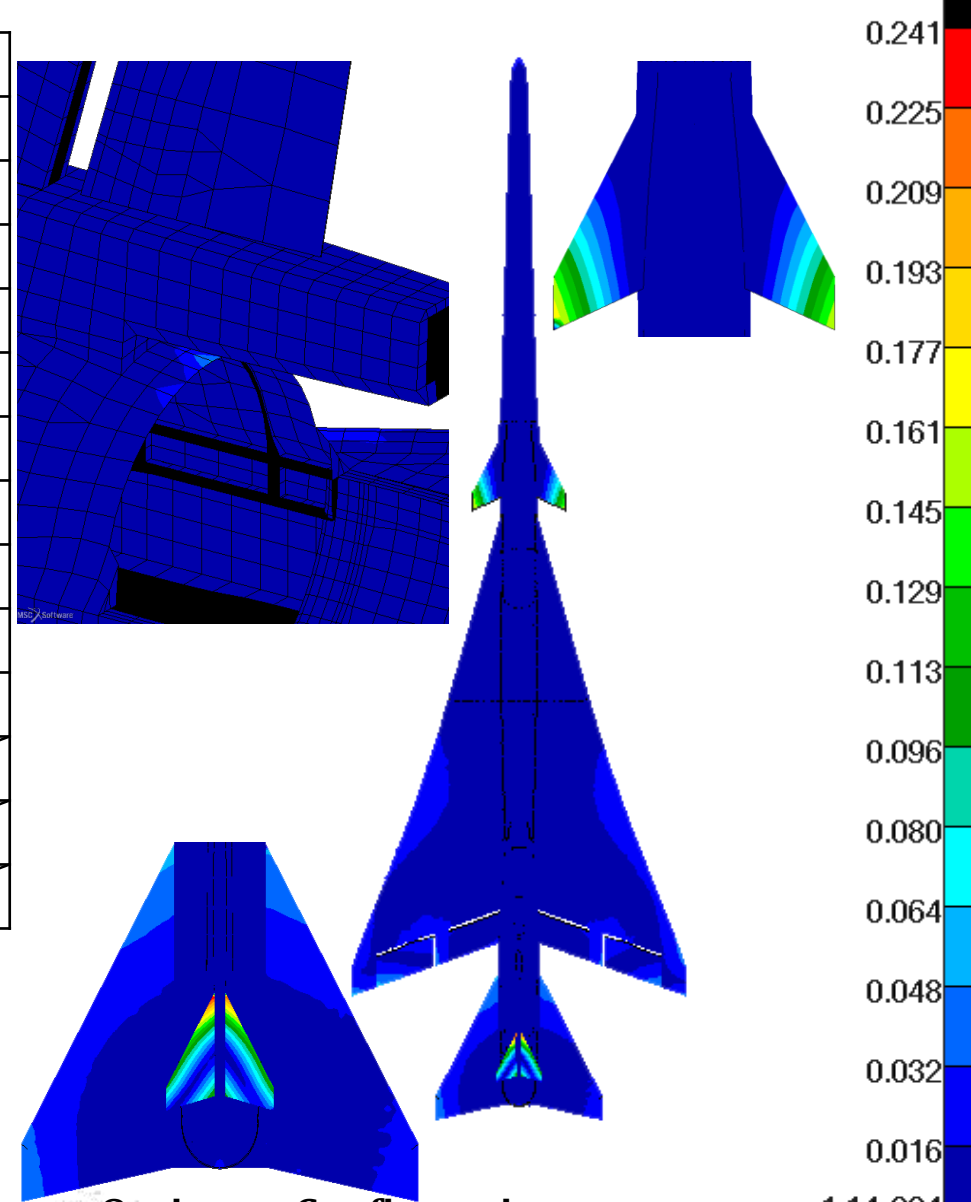


Start Configuration

Use Optimization

OBJ = 17.34

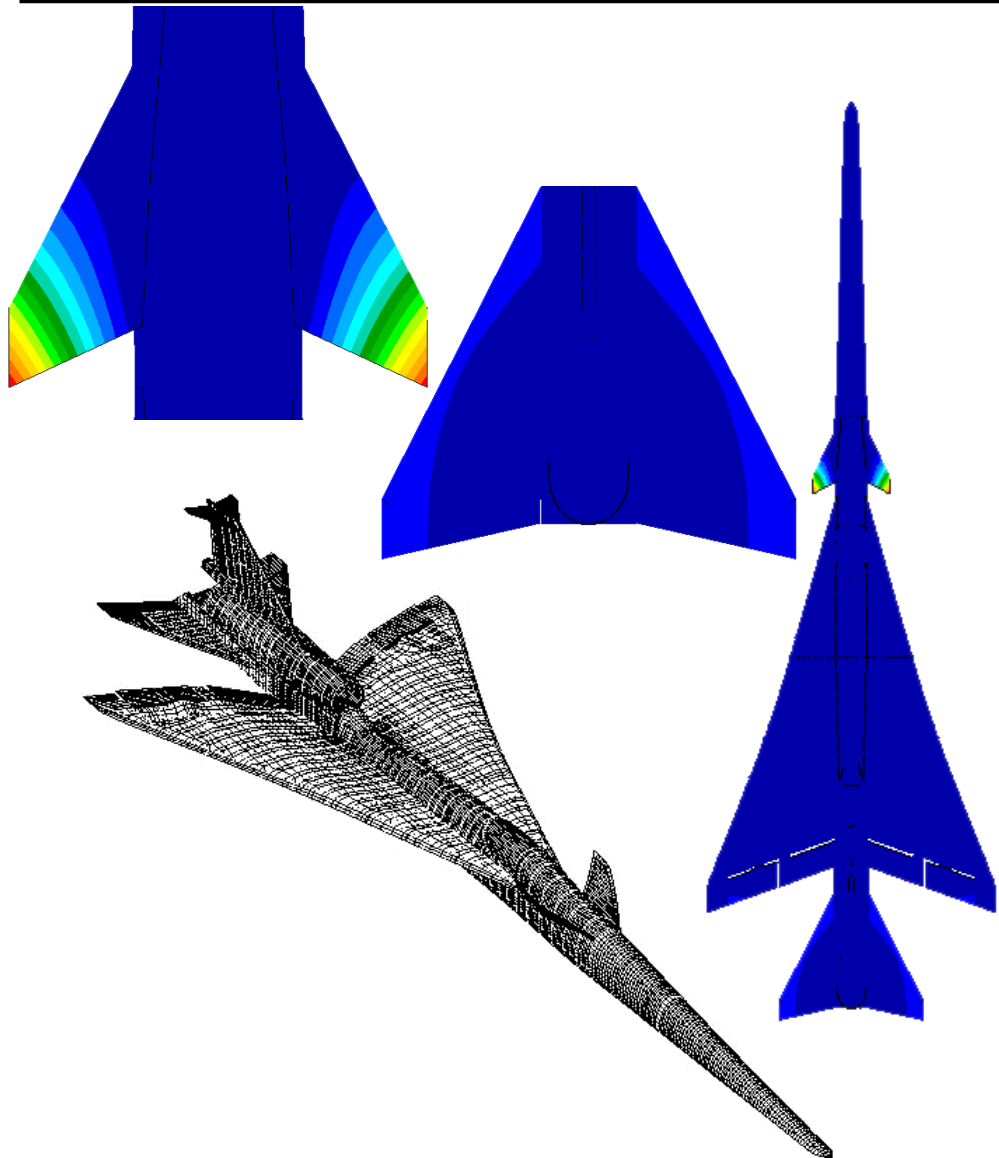
X_i	Value
1	0.4366
2	-1.126
3	0.2467
4	0.4031
5	.02364
6	0.6272
7	.04203
8	-.02643
9	.000992
10	0.1142
11	
12	
13	



Optimum Configuration

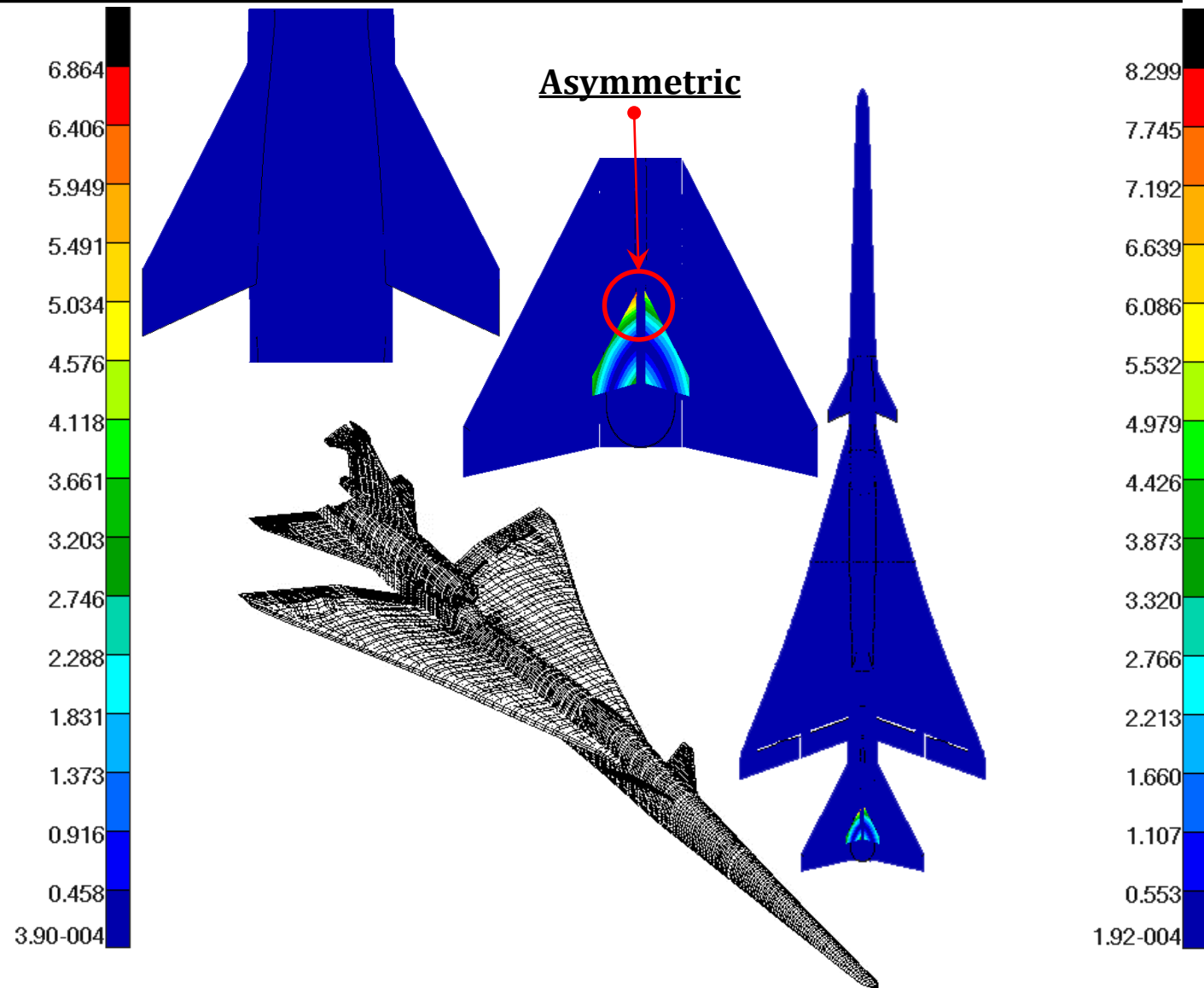


Mode 37: 30.79 Hz



symmetric canard bending

Mode 48: 42.96 Hz



symmetric ttail

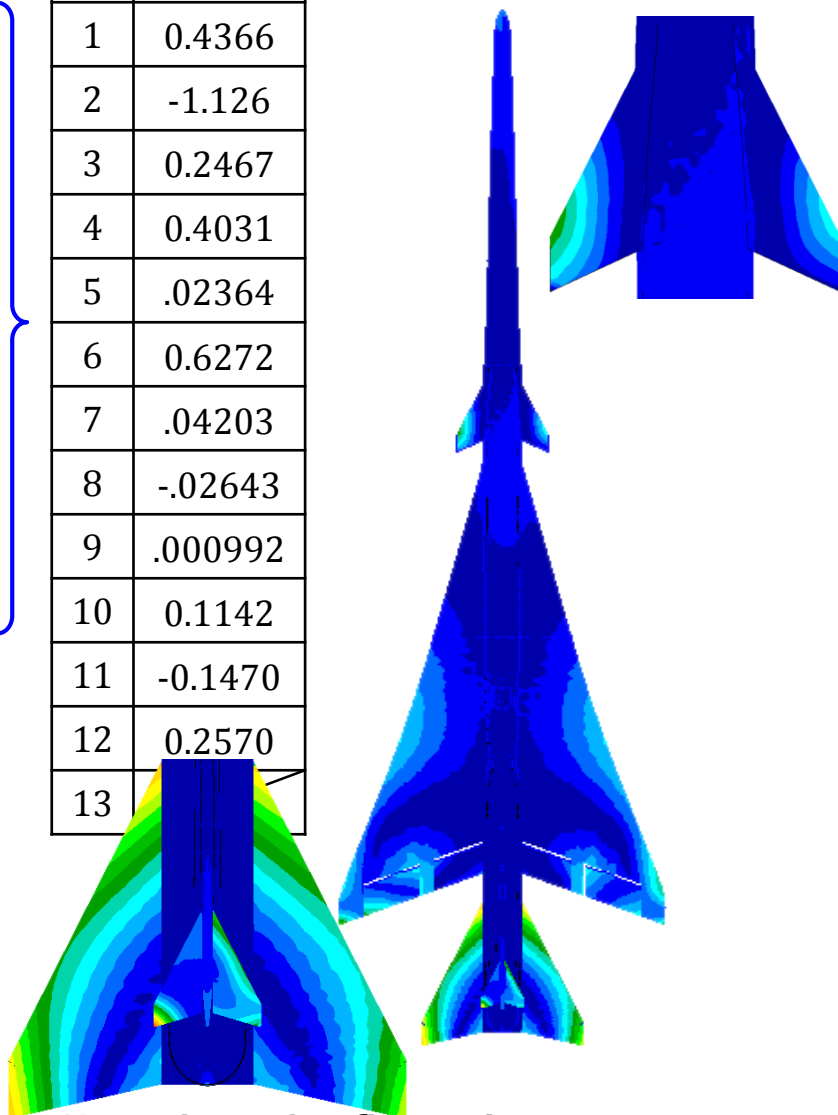
Optimization #2: $\{\Delta T\}_{t_o} = \{T\}_t - \{T\}_o$

Use least-squares surface fitting

OBJ=6.148

X_i	Value
1	0.4366
2	-1.126
3	0.2467
4	0.4031
5	.02364
6	0.6272
7	.04203
8	-.02643
9	.000992
10	0.1142
11	
12	
13	

X_i	Value
1	0.4366
2	-1.126
3	0.2467
4	0.4031
5	.02364
6	0.6272
7	.04203
8	-.02643
9	.000992
10	0.1142
11	-0.1470
12	0.2570
13	

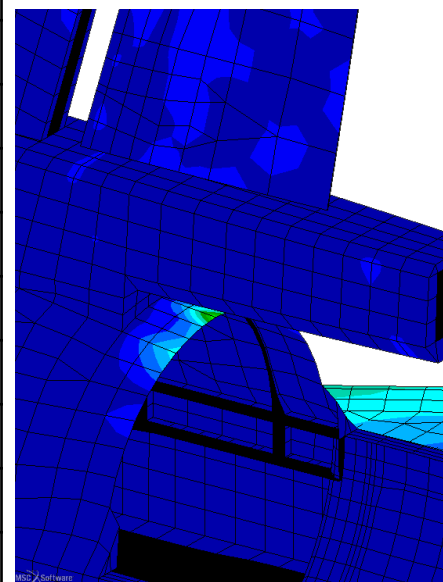


Start Configuration

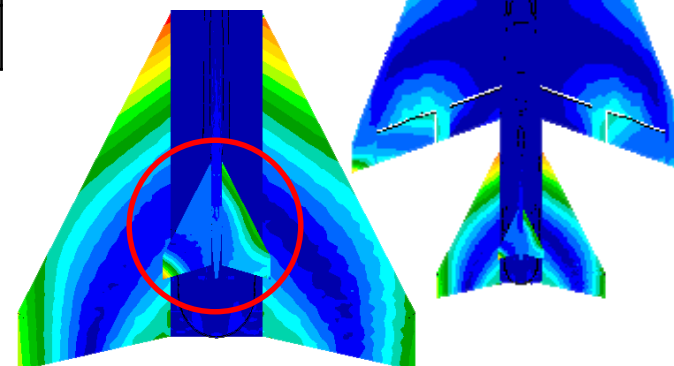
Use Optimization

OBJ=5.807

X_i	Value
1	0.4370
2	-1.152
3	0.2356
4	0.3962
5	.01778
6	0.6228
7	.04228
8	-.02570
9	-.000747
10	0.1161
11	-0.1477
12	0.2575
13	



Residual shape



Optimum Configuration

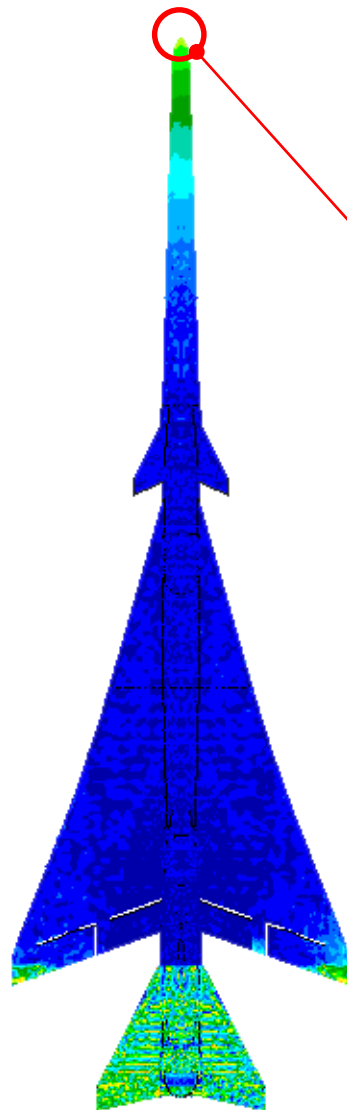
Optimization #3: $\{\Delta T\}_{t_o} = \{T\}_t - \{T\}_o$

Use least-squares surface fitting

OBJ=0.09566

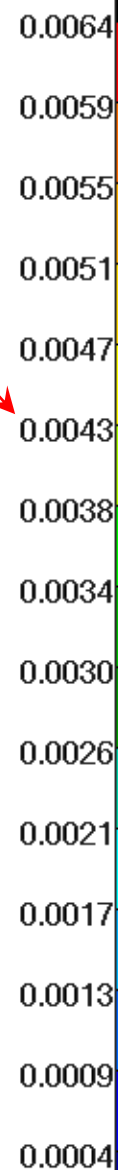
X_i	Value
1	0.4338
2	-1.152
3	0.2354
4	0.3961
5	.01920
6	0.6221
7	.04123
8	-.0265
9	-.000167
10	0.1165
11	-0.1475
12	0.2567
13	0.08358

0.085 inch



Start Configuration

inch

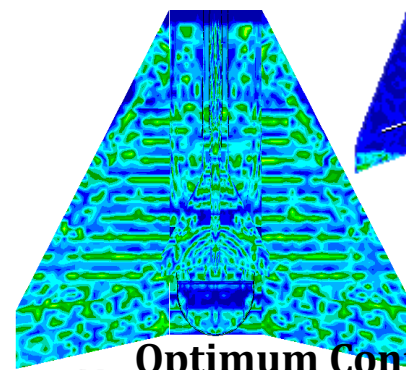
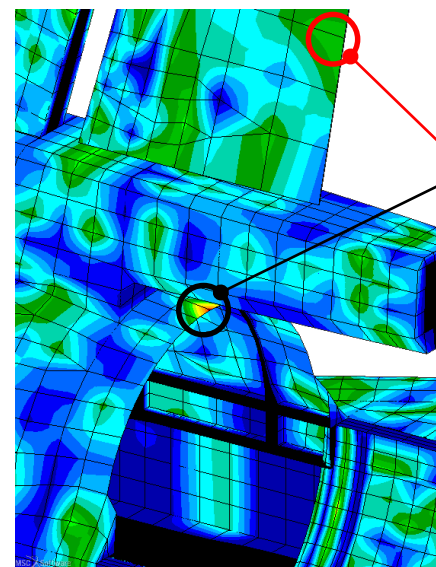


4.543-006

Use Optimization

OBJ=0.08819

X_i	Value
1	0.4336
2	-1.153
3	0.2353
4	0.3959
5	.01919
6	0.6220
7	.04120
8	-.0265
9	-.000292
10	0.1165
11	-0.1476
12	0.2567
13	0.08350



Optimum Configuration

inch



6.687-006



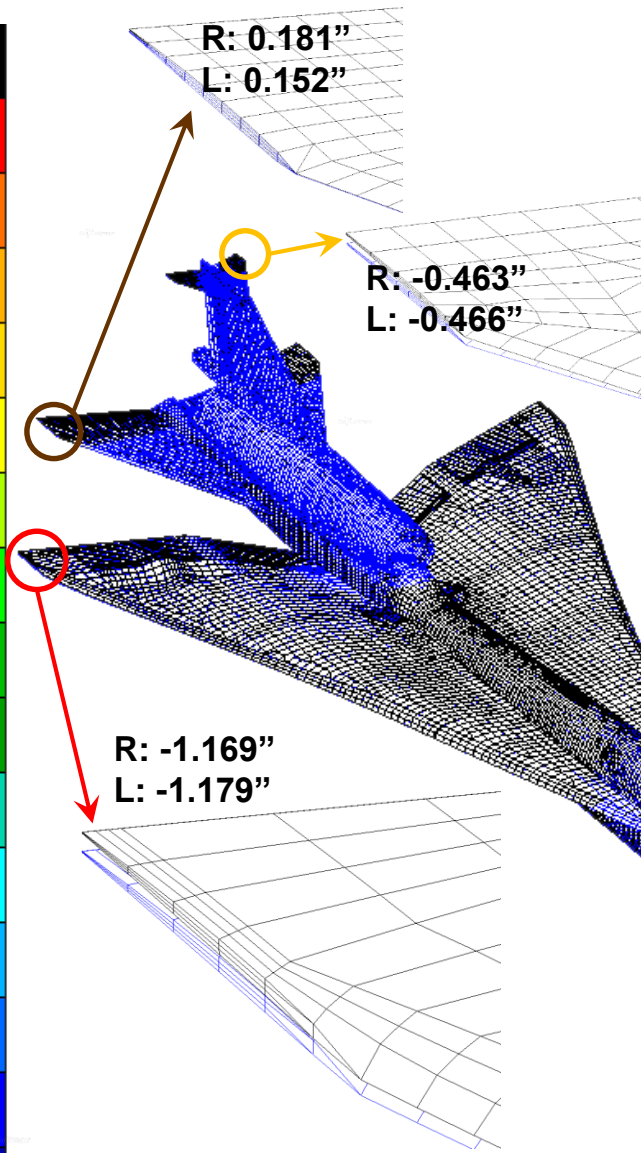
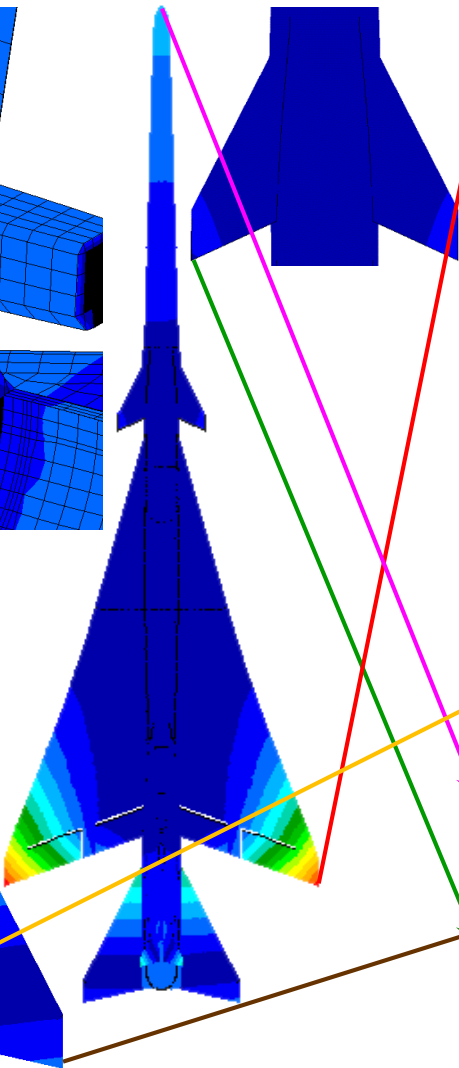
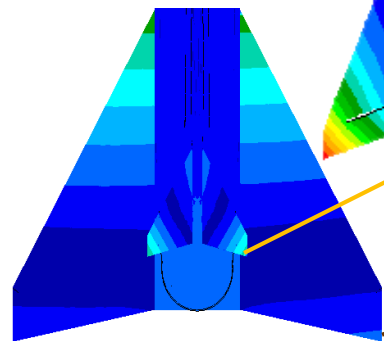
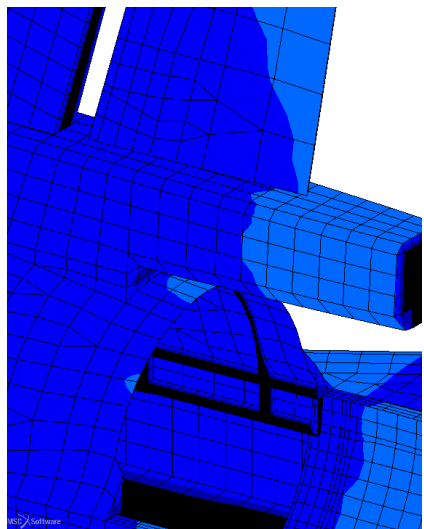
Optimization Results

DESVAR ID	Baseline	Optimization #1		Optimization #2		Optimization #3		Comments
		Start	Optimum	Start	Optimum	Start	Optimum	
1	0.0	0.4370	0.4366	0.4366	0.4370	0.4338	0.4336	Mode 7
2	0.0	-1.125	-1.126	-1.126	-1.152	-1.152	-1.153	Mode 9
3	0.0	0.2469	0.2467	0.2467	0.2356	0.2354	0.2353	Mode 11
4	0.0	0.4035	0.4031	0.4031	0.3962	0.3961	0.3959	Mode 15
5	0.0	.02350	.02364	.02364	.01778	.01920	.01919	Mode 17
6	0.0	0.6273	0.6272	0.6272	0.6228	0.6221	0.6220	Mode 19
7	0.0	.04194	.04203	.04203	.04228	.04123	.04120	Mode 20
8	0.0	-.02655	-.02643	-.02643	-.02570	-.0265	-.0265	Mode 22
9	0.0	.000856	.000992	.000992	-.000747	-.000167	-.000292	Mode 23
10	0.0	0.1141	0.1142	0.1142	0.1161	0.1165	0.1165	Mode 25
11	0.0			-0.1470	-0.1477	-0.1475	-0.1476	Mode 37
12	0.0			0.2570	0.2575	0.2567	0.2567	Mode 48
13	0.0					0.08358	0.08350	Residual
Maximum Error	1.174"	0.240"	0.241"	0.092"	0.085"	0.0064"	0.0088"	
Objective Function	1075.8	17.48	17.34	6.148	5.807	0.09566	0.08819	



Optimum Aircraft Configuration

$$\{\Delta T\}_t$$



	Baseline	Optimum	% difference
Weight (lb)	18499.99	18499.97	0.00
X-C.G. (inch)	836.0883	836.0881	0.00
Y-C.G. (inch)	-0.1896631	-0.1896621	0.00
Z-C.G. (inch)	100.6766	100.6766	0.00
I_{xx}	42680290.	42703310.	0.05
I_{yx}	-251146.3	-251316.5	0.07
I_{yy}	629919800.	629901800.	0.00
I_{zx}	-17221140.	-17213590.	-0.04
I_{zy}	23157.81	22989.41	-0.73
I_{zz}	661918400.	661910400.	0.00

— : Baseline Configuration
— : Optimum Configuration



Summary of Natural Frequencies before and after optimization

Mode	Frequency (Hz)			Notes
	Baseline	Optimum	% difference	
7	5.634	5.633	-0.02	First fuselage bending
9	9.045	9.034	-0.12	First wing bending + forward fuselage vertical bending + stabilator rotation
11	11.97	11.97	0.00	Forward fuselage vertical bending + first wing bending + stabilator rotation (Asymmetric)
15	14.76	14.76	0.00	Stabilator rotation
17	19.23	19.23	0.00	Wing tip bending + T-tail rotation + flap bending (Asymmetric)
19	20.08	20.08	0.00	T-tail rotation (Asymmetric)
20	20.54	20.55	0.05	Wing tip bending + T-tail rotation + aileron rotation + flap bending + forward fuselage vertical bending (Asymmetric)
22	21.75	21.76	0.05	Aileron rotation + flap rotation + T-tail bending + outboard wing bending torsion
23	22.16	22.17	0.05	Flap rotation + aileron rotation + wing tip bending + T-tail bending (Asymmetric)
25	22.70	22.70	0.00	Flap rotation + aileron rotation + T-tail bending (Asymmetric)
37	30.79	30.76	-0.10	Canard bending
48	42.96	42.97	0.02	T-tail bending (Asymmetric)



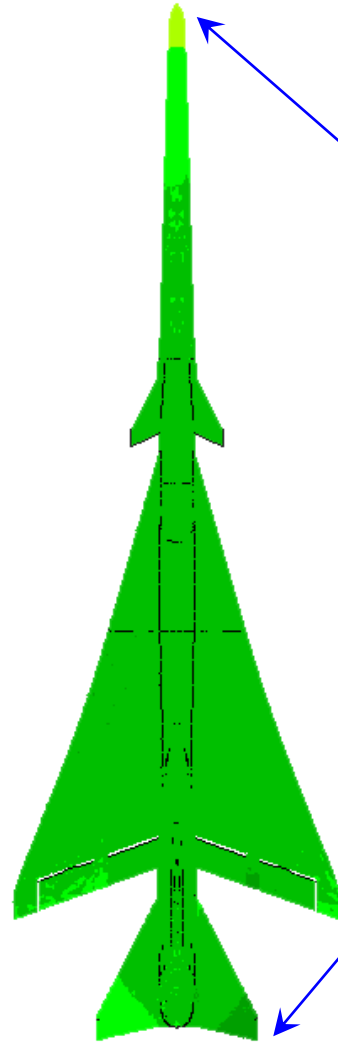
Conclusion

- ❑ In this study, the jig-shape optimization is performed using the two step approach.
 - ❖ The first step is computing the starting design variables using the **least squares surface fitting technique**.
 - ❖ The next step is the fine tune of the jig-shape using the **numerical optimization procedure**.
 - ❖ Assume **unconstrained** optimization
 - The maximum frequency change due to the jig-shape optimization is less than 0.12%.
 - The minor changes in mass moment of inertia are observed. (mostly less than 0.07%; maximum 0.73%)

- ❑ Thirteen basis function are used in this jig-shape optimization study.
 - ❖ Total of **twelve symmetric mode shapes** of the cruise weight configuration. (Asymmetric shapes exist)
 - ❖ **A residual shape** is also selected as a basis function.

- ❑ The maximum trim shape error of **1.174"** at the starting configuration becomes **0.0088"** at the end of the third optimization run.

Questions?



Trim Shape Error

